### UNIVERSITY OF CAMBRIDGE INTERNATIONAL EXAMINATIONS GCE Advanced Subsidiary Level and GCE Advanced Level

## MARK SCHEME for the May/June 2007 question paper

# 9702 PHYSICS

9702/31

Paper 31 (Advanced Practical Skills), maximum raw mark 40

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began.

All Examiners are instructed that alternative correct answers and unexpected approaches in candidates' scripts must be given marks that fairly reflect the relevant knowledge and skills demonstrated.

Mark schemes must be read in conjunction with the question papers and the report on the examination.

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- <b></b>	GCE A/AS LEVEL – May/June 2007	9702	31
Manipul	ation, measurement and observation		
Success	ful collection of data		
• •	surements mark for each set of readings for <i>V</i> and <i>n.</i>		
<b>(b)</b> Appa	aratus set up without help from supervisor.		
Range a	nd distribution of values		
(c) n = ?	l or 2 and <i>n</i> = 10 or 11 must be included and no more	e than a gap of three.	
Quality o	of data		
• • •	Judge by scatter of points about the best fit line. At least 5 plots are needed on the trend line for this r	mark to be scored.	
Presenta	ation of data and observations		
Table: la	ayout		
Each Igno	Imn headings ( $V/V$ , $1/V / V^{-1}$ only). Ignore <i>n</i> column. In column heading must contain a quantity and a unit re units in the body of the table. The must be some distinguishing mark between the qu	where appropriate.	
Table: ra	aw data		
	sistency of presentation of raw readings. alues of <i>V</i> must be given to the same number of dec	imal places.	
Table: c	alculated quantities		
Appl If V i If V i	ificant figures y to 1/V. s given to 2 s.f., then accept 1/V to 2 or 3 s.f. s given to 3 s.f., then accept 1/V to 3 or 4 s.f. s given to 4 s.f., then accept 1/V to 4 or 5 s.f.		
	es of 1/V correct. ck a value. If incorrect, write in the correct value. All	low small rounding error	ſS.
Graph: I	ayout		
	Axes Sensible scales must be used. Awkward scales (e.g Scales must be chosen so that the plotted points mu in both <i>x</i> and <i>y</i> directions. Indicate false origin w Scales must be labelled with the quantity which is be	ist occupy at least half the vith FO.	

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Graph: plott	ing of points	·	
Ring	bservations must be plotted. and check a suspect plot. Tick if correct. Re-plot if ir < to an accuracy of half a small square.	ncorrect.	
Graph: trend	l line		
Judg	of best fit (of 5 or 6) le by scatter of points about the candidate's line. le must be a fair scatter of points either side of the line ate best line if candidate's line is not the best line.		
Analysis, co	nclusions and evaluation		
Interpretatio	n of graph		
Read-off	otenuse of the Δ must be greater than half the length c s must be accurate to half a small square. r Δy/Δx (i.e. do not allow Δx/Δy).	of the drawn line.	
	pt from graph or substitute correct read-offs into y = m origin has been used then label FO.	x + c.	
Drawing cor	clusions		
•	<i>E.</i> etween <b>4–5V</b> . Should be 1/y-intercept. e value. Unit required. 2/3 s.f.		
Method of	$R_1/R_2$ . <b>.19–0.23</b> unless supervisor has used different resistor of working must be correct. s given then this mark <b>cannot</b> be scored. 2/3 s.f.	S.	

	www	www.dynamicpapers.com		
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#### 2 Manipulation, measurement and observation

## Successful collection of data

<ul> <li>(iii) Position of centre of mass of ball at equilibrium</li> <li>(Value &lt; 1m and appropriate unit. No more than 1 d.p. in cm.)</li> </ul>	[1]
<ul><li>(b) (i) Position of centre of mass of ball when displaced</li><li>(ii) Position of centre of mass of ball at maximum height</li></ul>	[1] [1]
(d) Second position of centre of mass of ball when displaced	[1]
(d) Second position of centre of mass of ball at maximum height	[1]
(b)/(d) Repeated measurements for maximum height	[1]
Quality of data	
(d) Bigger x gives bigger h	[1]
Presentation of data and observations	
Display of calculation and reasoning	
<ul> <li>(b), (d) Values of <i>x</i> calculated correctly. (Displaced – equilibrium position) Both values required. Unit need not be stated but must be consistent. Calculations must be checked.</li> </ul>	[1]
(b), (d) Values of <i>h</i> calculated correctly. (Max height – equilibrium position) Both values required. Unit need not be stated but must be consistent. Calculations must be checked.	[1]
(e) Correct calculation to check proportionality Possibilities include: Two calculations of x <sup>2</sup> /h or ratio of x <sup>2</sup> values and ratio of h values calculated.	[1] s both
Analysis, conclusions and evaluation	
Drawing conclusions	
(e) Conclusion Sensible comments supported by calculations and suggested relation. Incorrect ideas score zero.	[1]
Estimating uncertainties	
<ul> <li>(c) (ii) Percentage uncertainty in <i>h</i>.</li> <li>Uncertainty in <i>h</i> is 2–10 mm. Whole numbers only.</li> <li>If repeated readings have been done then the uncertainty could be half the range.</li> <li>Correct ratio idea required, ×100 stated/implied.</li> </ul>	[1]

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[4]

[4]

#### Identifying limitations

- (f) (i) Relevant points must be underlined and ticked. Some of these might be:
  - A Ruler not vertical.
  - B Locating the <u>centre</u> of the ball (when reading ruler).
  - **C** Parallax error.
  - **D** Establishing <u>when</u> the ball is at its maximum displacement.
  - **E** Only two displacements (are not enough to validate the conclusion).
  - **F** Difficulty in the <u>release</u> of the mass (reference to force/vertical plane).

#### Suggesting improvements

- (f) (ii) Relevant points must be underlined and ticked. Some of these might be:
  - A Sensible method to ensure ruler vertical.
  - **B** Place the rule as close as possible to the mass/mark the <u>centre</u> of the ball with mark or pointer/use the bottom/top of the ball.
  - **C** Measure at eye level/repeat to get eye in the right place/place the rule as close as possible to the mass.
  - D Use video camera (play back) frame by frame/slow motion/position sensor <u>above</u> or <u>below</u>.
  - E Need a wider range of displacements **and** plot a graph/find mean k.
  - **F** Use a clamp/electromagnet to release the mass.

Do not allow 'repeated readings', 'human error'. Do not allow 'use a computer to improve the experiment'.

[Total: 20]